Mögliche Szenarien:

* Emergency brake leading vehicle
* One or more data is lost
  + Structural adaptation of the system
* Weather change, worse/ better road condition
* Speedlimit lower than current speed
* Leading vehicle drives faster than speedlimit
* Leading Vehicle accelerates at higher speed limit
* Leading vehicle drives slower than speed limit
* Leading vehicle brakes
* (Other vehicle shears in between the two vehicles)
* Combination

Wheel Speed Sensor: z.B: für jedes Rad

Find redundant services

Tasks:

* Setup control for every possible action
  + Keycallback or own window with buttons

Erst Failure bei Szenario, dann Lösung mit unserem System

Für nächste Woche: Szenarie implementieren

Distance and Speed Controller swap maybe

Safety supervisor – Decision Tree combination

Severity, Controlloability, Where, What (Omission, Failure, Delay…) = Supervisor